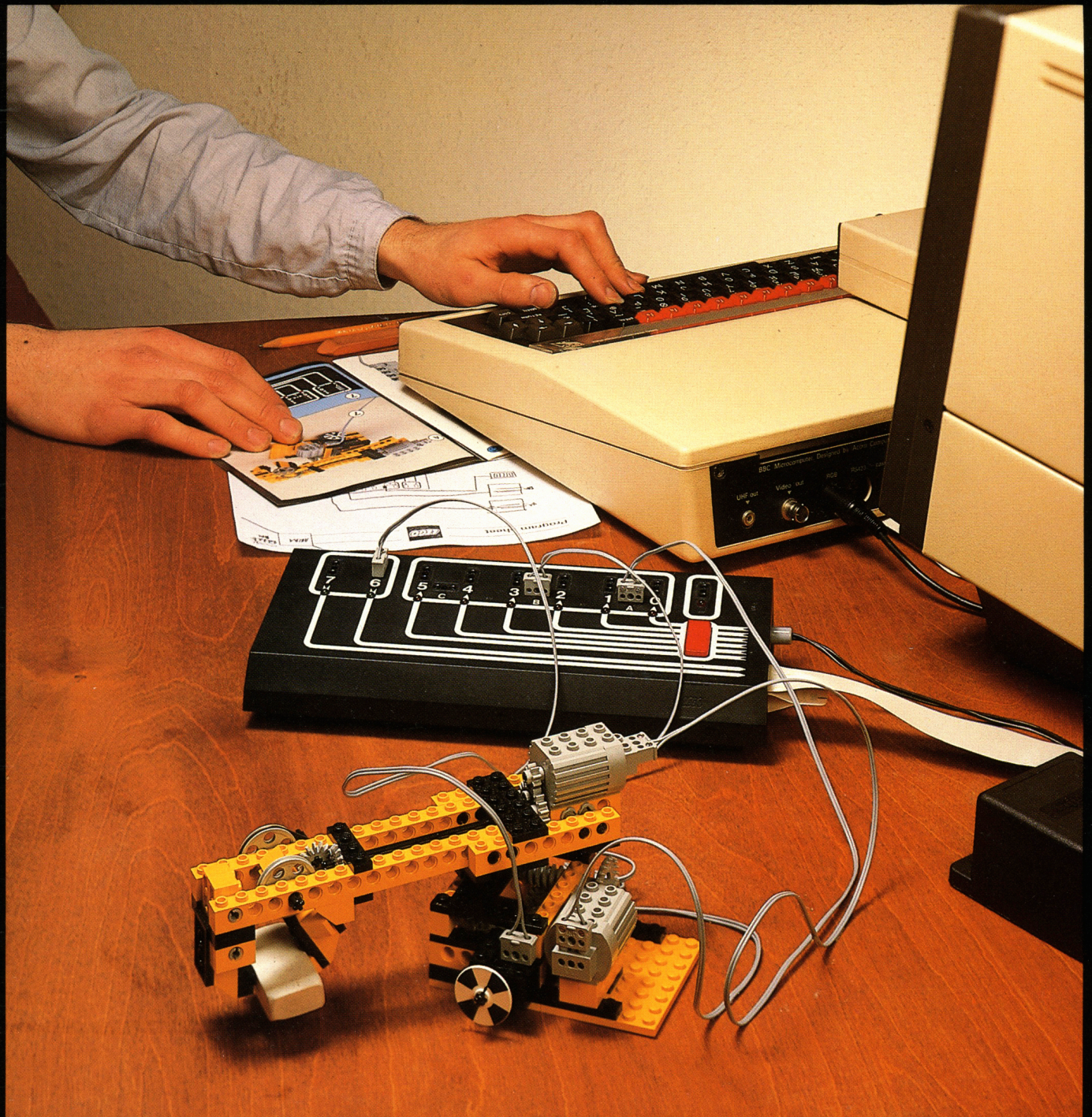


# 1455 Technic







## Programmable Systems


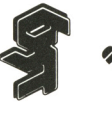
### Classroom materials







 <b>Lines</b> © 1986 LEGO Group		SHIFT f0 ANY VALUE <b>7</b>	SHIFT f1 ANY VALUE <b>6</b>	◀SHIFT f CTRL f▶ <b>5</b>	CTRL f3 DISK DIRECTORY <b>4</b>	CTRL f4 MAIN/BOXED DISPLAY <b>3</b>	CTRL f5 END <b>2</b>	CTRL f6 WIPE <b>1</b>	CTRL f7 PRINT <b>0</b>	CTRL f8 INSERT LINE LOAD	CTRL f9 DELETE LINE SAVE	 <b>CONTROL SOFTWARE</b>
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 <b>Lines</b> © 1986 LEGO Group		SHIFT f0 ANY VALUE <b>7</b>	SHIFT f1 ANY VALUE <b>6</b>	◀SHIFT f CTRL f▶ <b>5</b>	CTRL f3 DISK DIRECTORY <b>4</b>	CTRL f4 MAIN/BOXED DISPLAY <b>3</b>	CTRL f5 END <b>2</b>	CTRL f6 WIPE <b>1</b>	CTRL f7 PRINT <b>0</b>	CTRL f8 INSERT LINE LOAD	CTRL f9 DELETE LINE SAVE	 <b>CONTROL SOFTWARE</b>
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 <b>Lines</b> © 1986 LEGO Group		SHIFT f0 ANY VALUE <b>7</b>	SHIFT f1 ANY VALUE <b>6</b>	◀SHIFT f CTRL f▶ <b>5</b>	CTRL f3 DISK DIRECTORY <b>4</b>	CTRL f4 MAIN/BOXED DISPLAY <b>3</b>	CTRL f5 END <b>2</b>	CTRL f6 WIPE <b>1</b>	CTRL f7 PRINT <b>0</b>	CTRL f8 INSERT LINE LOAD	CTRL f9 DELETE LINE SAVE	 <b>CONTROL SOFTWARE</b>
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 <b>Lines</b> © 1986 LEGO Group		SHIFT f0 ANY VALUE <b>7</b>	SHIFT f1 ANY VALUE <b>6</b>	◀SHIFT f CTRL f▶ <b>5</b>	CTRL f3 DISK DIRECTORY <b>4</b>	CTRL f4 MAIN/BOXED DISPLAY <b>3</b>	CTRL f5 END <b>2</b>	CTRL f6 WIPE <b>1</b>	CTRL f7 PRINT <b>0</b>	CTRL f8 INSERT LINE LOAD	CTRL f9 DELETE LINE SAVE	 <b>CONTROL SOFTWARE</b>
---	--	-----------------------------------	-----------------------------------	---------------------------------	---------------------------------------	---	----------------------------	-----------------------------	------------------------------	--------------------------------	--------------------------------	--

# Manual controller keypad



c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

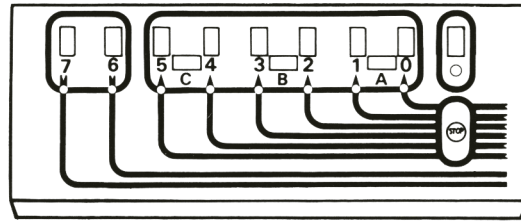
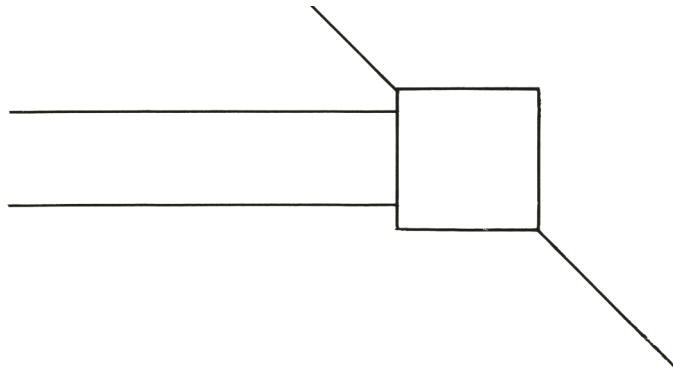
c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

c		b		a	
5	4	3	2	1	0

© 1986 LEGO Group

# Program sheet



IN		OUT					
7	6	5	4	3	2	1	0

# Assessment



## **a** Analysis

Stating the problem accurately  
 Exploring the problem  
 Developing deeper understanding  
 Developing criteria

## **S** Finding and developing the best solution

Evaluating each solution  
 Choosing the best solution  
 Modelling the best solutions

## **C** Communication

Discussion with others  
 Listening to other's ideas  
 Drawing sketches and diagrams  
 Writing a report  
 Giving a talk

## **i** Finding and developing ideas

Discussion with others  
 Looking and thinking up ideas  
 Investigating ideas  
 Finding several solutions

## **e** Evaluation

Using the criteria to carry out tests  
 Analysing the tests' results  
 Making modifications when necessary

## **t** Teamwork

Contributing ideas  
 Sharing work equally  
 Working cooperatively

<i>Assignment</i>	<i>Notes</i>

<i>Assignment</i>	<i>Notes</i>

<i>Assignment</i>	<i>Notes</i>

<i>Assignment</i>	<i>Notes</i>

<i>Assignment</i>	<i>Notes</i>

# Assignment: 0



Introduction to  
the materials

A0a

You will need

- Resources booklet
- Program sheet
- Assessment sheet

You are going to

Learn how to use the materials

Using the materials you are going to learn about three different ways to control devices:

- human control
- mechanical control
- electronic control

To do this, you will be given Assignment cards, like this one. This assignment, Assignment 0, comes in three parts, A0a, A0b and A0c.

To help you in all the assignments, there are the Resources booklet, the Program sheet and the Assessment sheet. Make sure you have these in front of you for Assignment 0.


## Assignment cards

The Assignment cards, like this one, are designed to be as easy to use as possible. On the top right-hand corner of each one you will find a reference number, A0a on this one (that is Assignment 0, part a). Underneath this you will find a statement of what you are going to do in the assignment.

The box on the top left-hand side of the card outlines what you will need in order to do the assignment. You should make sure you have these before you start.

The rest of the card tells you what to do. Drawings and sample programs take you through the activity. Where extra help is available in the Resources booklet, you are shown where to find it by the figure in the middle column like this:



**Assignment: 2d**  Introduction to computer control **A2d**

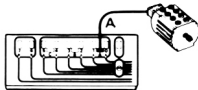
**You will need**

- Computer system and LEGO Lines disk
- A motor
- Resources booklet R8 R10 R14
- Program sheets

**You are going to**

Learn how to program a motor to reverse.

Connect a motor to the interface as shown.



## Program sheet

Use resources page **R11** to discover what you will be writing in each of the columns.

# Assignment: 0



Introduction to  
the materials

A0a

You will need

Resources booklet  
Program sheet  
Assessment sheet

You are going to

Learn how to use the materials

Using the materials you are going to learn about three different ways to control devices:

- human control
- mechanical control
- electronic control

To do this, you will be given Assignment cards, like this one. This assignment, Assignment 0, comes in three parts, A0a, A0b and A0c.

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**Assignment: 2d** Introduction to computer control **A2d**

You will need

- Computer system and LEGO Lines disk
- A motor
- Resources booklet R8 R10 R14
- Program sheets

You are going to

Learn how to program a motor to reverse.

Connect a motor to the interface as shown.

## Program sheet

Use resources page **R11** to discover what you will be writing in each of the columns.



# Assignment: 0



Introduction to  
the materials

A0c

You will need

Assessment sheet  
Resources booklet

You are going to

Learn how to use the  
Assessment sheet

## Assessment sheet

This is to help you measure the success of what you are doing and of what you have learnt. At the top there are headings for you to use to describe how you have got on, next to boxes containing letters (these letters also appear on the bottom of every Assignment sheet). Help is available on these headings on the following Resources booklet pages:



- 1 What does **i** stand for?
- 2 Where would you look to find out more about what **a i s e c** and **t** stand for?
- 3 What are *Criteria*?
- 4 If you were asked how well you thought your group worked as a team, what questions would you ask yourself?
- 5 **c** has five elements in it. Which do you think will be the most difficult for you to achieve?
- 6 Do you think you will use all the items on the Assessment sheet in every single assignment you do?
- 7 Are there any terms you can't find out about on the Assessment sheet?
- 8 Fill in an Assessment sheet for Assignment 0, describing what you think you have learnt from answering these questions.

<b>Assessment</b>			
<b>a</b> <b>Analysis</b> Stating the problem accurately Exploring the problem Developing deeper understanding Developing criteria	<b>S</b> <b>Finding and developing the best solution</b> Evaluating each solution Choosing the best solution Modelling the best solutions	<b>C</b> <b>Communication</b> Discussion with others Listening to other's ideas Drawing sketches and diagrams Writing a report Giving a talk	
<b>i</b> <b>Finding and developing ideas</b> Discussion with others Looking and thinking up ideas Investigating ideas Finding several solutions	<b>e</b> <b>Evaluation</b> Using the criteria to carry out tests Analysing the tests' results Making modifications when necessary	<b>t</b> <b>Teamwork</b> Contributing ideas Sharing work equally Working cooperatively	
<i>Assignment</i>	<i>Notes</i>		



# Assignment: 1a



Introduction to programmable systems

A1a

## You will need

- Computer system with disk drive
- LEGO Lines disk
- 1 motor model and light brick
- Resource booklet

## You are going to

Use a computer program to control a model system.

Connect computer system and insert disk.

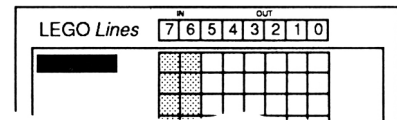


Collect model and connect it to the interface as directed in the Resources booklet.



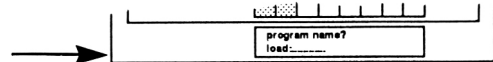
## Loading LEGO Lines

Press **SHIFT BREAK** to autoboot LEGO Lines



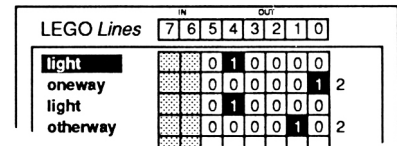
## Loading a program

Press **CTRL f8** to load program — this message should appear



Type **MLA** and then press **RETURN** to load program **MLA**.

*This program is designed to turn a light on, rotate a motor one way for two seconds, turn the light on again and rotate the motor the other way for another two seconds.*



## Running the program

Press **TAB** to run the program — check that the system performs correctly. If not



and then



## Changing the program



Alter the time of rotation

Press **↓** then **→** and check that the cursor block has moved down and across

Press **DELETE** to remove the time on this line:

Oneway ■ ■ 0 0 0 0 0 1 2.0

Enter a number between 1.0 and 3.5. Check to see it is entered correctly.

Press **TAB** to run the program. Then copy the program onto a Program sheet and describe what it does.

## Enter more instructions to repeat the sequence

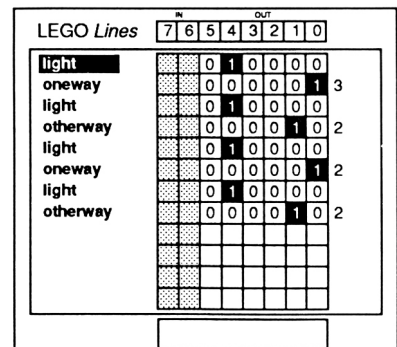
Press **↓** until the cursor block reaches the first blank line.

Copy the original instructions

- Use: Letter keys for labels
- Red keys for output values
- Numbers for timing or counting
- RETURN** to go to the next line.



Press **TAB** to run program and then produce a printout of this 'new' program and describe what it does.



a i s e c t

# Assignment: 1 b



Introduction to programmable systems

A1b

You will need

- Manual controller and keystrip
- Two-motor model (1090 D or 1090 E)
- Resources booklet R6, R8
- Program sheets

You are going to

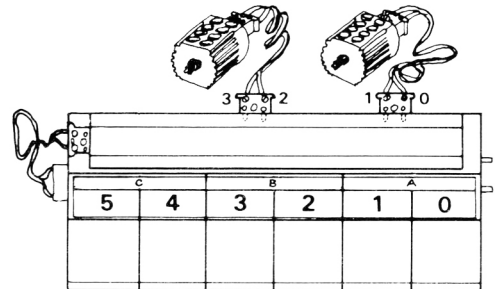
Control a model using the manual controller.

Connect a two-motor model to the manual controller as shown in the Resources booklet.

Press each key on the controller reasonably hard in turn.

Note what happens to the model.

A summary of your actions is given below:



The 1 means that key 1 is pressed or on

	5	4	3	2	1	Ø
Key 0	Ø	Ø	Ø	Ø	Ø	1
Key 1	Ø	Ø	Ø	Ø	1	Ø
Key 2						
Key 3						
Key 4						
Key 5						

Draw this table and complete it.

Try pressing keys 1 and 3 at the same time:

	5	4	3	2	1	Ø
Key 1 and Key 3	Ø	Ø	1	Ø	1	Ø

What happens to the model?

Why?

Check the direction the motors turn when you press keys 2 and Ø at the same time. If this is not the same, can you change the leads round so it is?

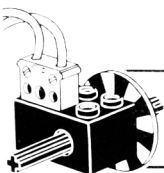
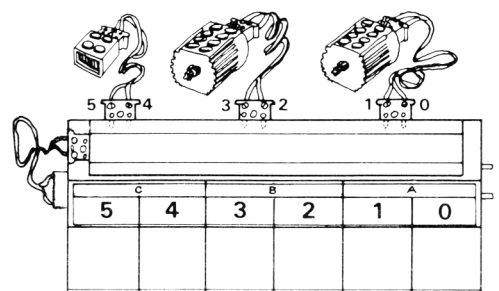


Here is a sequence of instructions.

	5	4	3	2	1	Ø	time
light on	Ø	1	Ø	Ø	Ø	Ø	5.0
one way	Ø	Ø	Ø	1	Ø	1	10.0
light on	Ø	1	Ø	Ø	Ø	Ø	5.0
other way	Ø	Ø	1	Ø	1	Ø	10.0

Instead of a key to press, we now have a *label* (to describe what is happening) and a time value to tell you how long to do it.

Now write some programs (on the program sheet) and try them out. Describe what you intend your models to do, and whether they do it.



a i s e c t

# Assignment: 2a



## Introduction to computer control

## A2a

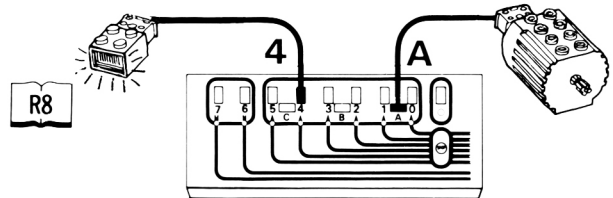
### You will need

- Computer system and LEGO Lines disk
- A motor and a light brick
- Resources booklet

### You are going to

Learn how to control a motor and light brick.

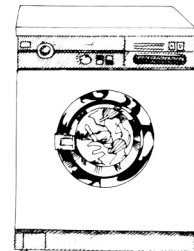
Take a motor and a light brick from your model and connect them to the interface as shown.



This material may be freely photocopied for use in the purchasing institution only.

**A washing machine manufacturer needs a control program which will spin clothes at the end of the wash cycle for 5 seconds.**

The LEGO motor represents the washing machine motor.



### Possible solution

- Press **SHIFT BREAK** to load LEGO Lines.
- Press **CTRL f8** to load program.
- Type **ONE** press **RETURN** to load ONE.
- Press **TAB** to test program and describe what this instruction does.



	IN							OUT			
LEGO Lines	7	6	5	4	3	2	1	0			
motor								1	5		

**An electric fan (represented by the LEGO motor) is required to come on for 8 seconds when a button is pressed.**

### Possible solution

- Change time of last solution
- to move cursor block to 'time'
- Press **DELETE**
- Press **8** to enter new time.
- Press **TAB** to test program and describe what it does
- look especially at the interface.



**An outside light is required to come on for 8 seconds when a button is pressed.**

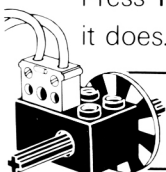
### Possible solution

- Press **f7** to set bit 0 off.
- Press **f3** to set bit 4 on. (Look for a '1' in column 4).
- DELETE** label and enter another word to describe what is taking place.
- Press **TAB** to test program and describe what it does.



	IN							OUT			
LEGO Lines	7	6	5	4	3	2	1	0			
light				1	0	0	0	0	8		

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a i s e c t

# Assignment: 2b



Introduction to computer control

A2b

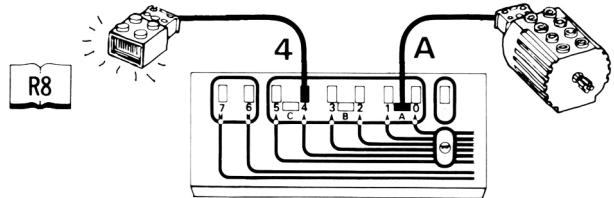
## You will need

- Computer system and LEGO Lines disk
- A motor and two light bricks
- Resources booklet R8, R10
- Program sheets

## You are going to

Learn how to control two or more output devices.

Use a light brick and a motor and connect them to the interface as shown.



A program is required which operates a fairground ride (represented by the LEGO motor) and a light which shows that the ride is in progress for 5 seconds.

### Possible solution

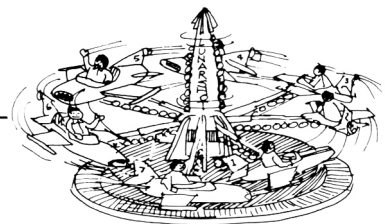
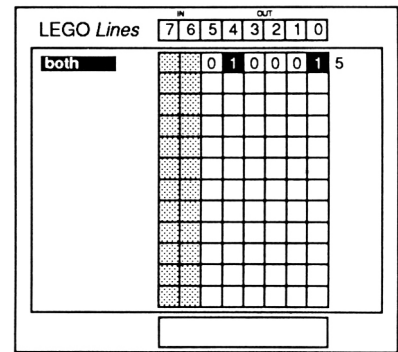
Connect motor to output bits A and lamp to output bits 4 on the interface.

Press **CTRL f8** to load program.

Type **TWO** press **RETURN** to load TWO.

Press **TAB** to test program.

Describe what happens on screen, on the interface and to the motor and light.



Improve the fairground ride to include two lights.

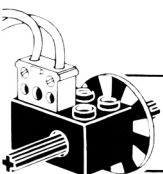
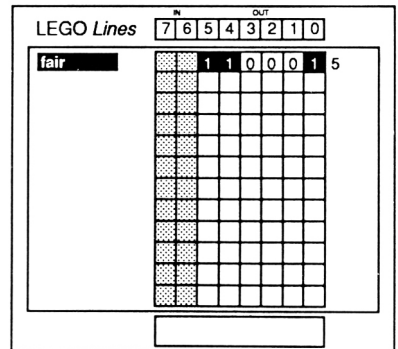
### Possible solution

Connect another light brick to the interface.

Change the line so that both the lights and the motor are on for 5 seconds.

Press **TAB** to test program.

Make a record of your program on the Program sheet, obtain a printout of it (by pressing **CTRL f7**) and describe how it solves the problem.



a i s e c t

# Assignment: 2c



Introduction to computer control

A2c

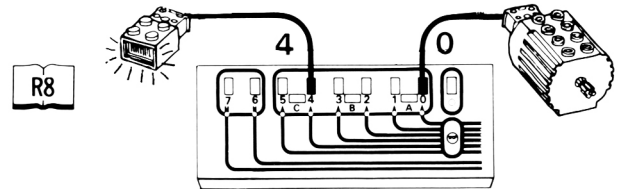
## You will need

- Computer system and LEGO Lines disk
- A motor and two light bricks
- Resources booklet R8, R10
- Program sheets

## You are going to

Learn how to program a sequence of instructions.

Connect the light brick and the motor to the interface as shown.



A program is needed which will turn on a light 10 seconds before a motor is started up.

### Possible solution

Connect motor to output bit 0.

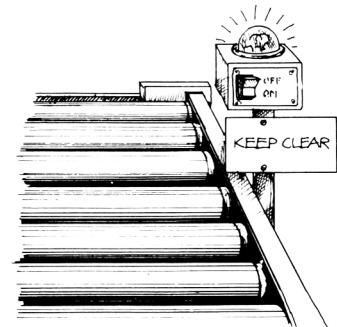
Connect lamp to output bit 4.

Press **CTRL f8** to load a program.

Type **THREE** press **RETURN** to load program **THREE**.

Press **TAB** to test program and describe what happens.

LEGO Lines		IN					OUT										
		7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
light					0	1	0	0	0	0	0	0	0	0	0	10	
motor					0	0	0	0	0	0	0	1	5			5	



Modify the solution to turn on another lamp for 5 seconds after the motor has been turned off.

### Possible solution

Connect another light brick to the interface.

Modify the program by adding an extra line.

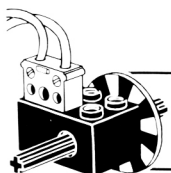
Position the cursor block at the start of this line and test it by pressing **COPY**.

Test the new program by pressing **TAB**.

Make a record of your program on the Program sheet, obtain a printout of it (by pressing **CTRL f7**) and describe how it solves the problem.



LEGO Lines		IN					OUT										
		7	6	5	4	3	2	1	0	7	6	5	4	3	2	1	0
light					0	1	0	0	0	0	0	0	0	0	0	10	
motor					0	0	0	0	0	0	1	5				5	
light					1	0	0	0	0	0	0	0	5			5	



a i s e c t

# Assignment: 2d



## Introduction to computer control

A2d

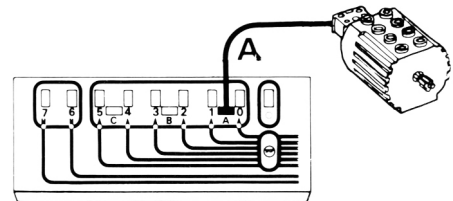
### You will need

- Computer system and LEGO Lines disk
- A motor
- Resources booklet R8, R10, R14
- Program sheets

### You are going to

Learn how to program a motor to reverse.

Connect a motor to the interface as shown.



A program is needed to raise a barrier, pause and then lower the barrier again.

The solution should operate when a button (TAB) is pressed. The LEGO motor represents the barrier motor.

### Possible solution

Press **CTRL f8** to load program.

Type **FOUR** press **RETURN** to load FOUR.

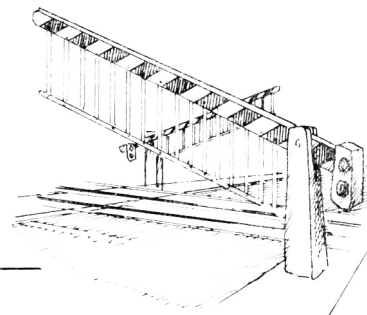
Press **TAB** to test program.

Can you change the program so that the barriers pause for at least 15 seconds before starting again?

Draw a structured flow diagram giving a solution to this problem and describe your solution.



LEGO Lines	IN							OUT			
	7	6	5	4	3	2	1	0	10	10	
oneway									1	0	10
pause									0	0	0
otherway									1	0	10



### Investigation

Change the last line of the program so that the output bits 0 and 1 are both on.

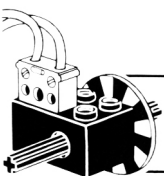
Press **COPY** to test new line.

Explain what happens.

Can you think of any everyday situations where this feature could be of any practical use?



LEGO Lines	IN							OUT			
	7	6	5	4	3	2	1	0	10	10	
oneway									1	0	10
pause									0	0	0
otherway									0	0	10



a i s e c t





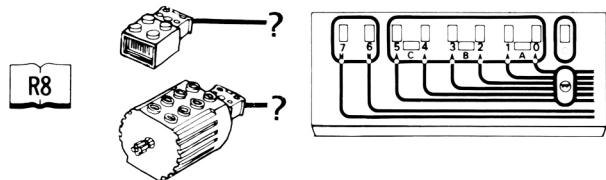
### You will need

- Computer system and LEGO Lines disk
- A motor and two light bricks
- Resources booklet R7, R8, R10, R11, R13
- Program sheets

### You are going to

Learn how to program a REPEAT FOREVER loop.

Use a motor and a light brick. You will have to work out from the programs where to connect them on the interface.



**A burglar alarm system requires a light which will flash on and off until a reset button is pressed.**

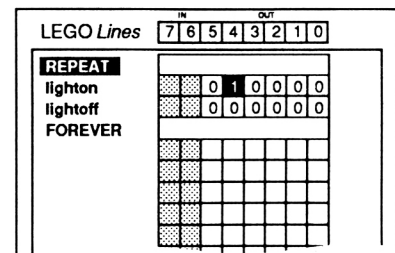
### Possible solution

Press **CTRL f8** to load program.

Type **FIVE** press **RETURN** to load FIVE.

Connect the light brick to the correct output, once you have loaded the program.

Press **TAB** to test program.



### Investigation

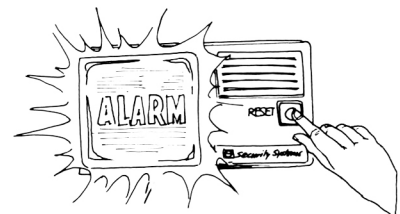
Press **SPACE** to halt program.



Press **SPACE** to continue program.

Press **ESCAPE** to end program.

The **ESCAPE** key acts as a reset button. When you press it, the program stops and the light no longer flashes.

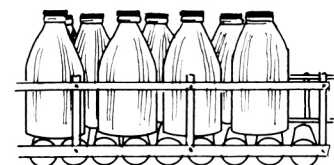


Copy the instructions onto a Program sheet and describe what is happening.

**Design a program to control a machine which presses tops onto milk bottles as they move along a continuous conveyor belt.**

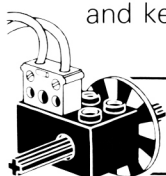


What kind of device makes a conveyor move?  
 What kind of device can press a top onto a bottle?  
 How will the process of pressing the tops start and stop?



Use your answers to these questions to develop a solution to the problem using the LEGO materials.

Use the Program sheet to develop your solution and keep a record of your progress.



a i s e c t



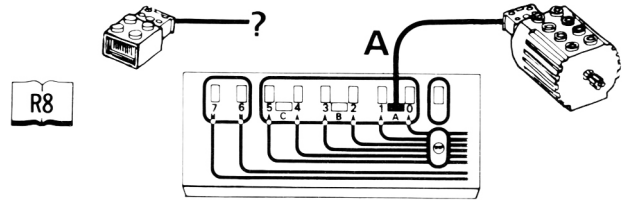
### You will need

- Computer system and LEGO Lines disk
- A motor and two light bricks
- Resources booklet R7, R8, R10, R11, R13
- Program sheets

### You are going to

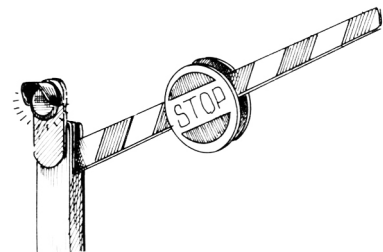
Learn how to program a REPEAT ENDREPEAT loop to run a set of instructions a number of times.

Use a motor and a light brick. Connect the motor to the interfaces as shown. You will have to work out from the programs where to connect the light brick.



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A level crossing barrier uses a flashing light to warn motorists it is closing. Design a program which will make this light flash 10 times.



### Possible solution

Press **CTRL f8** to load program.

Type **SIX** press **RETURN** to load SIX.

Connect the light brick to the correct output, once you have loaded the program.

Press **TAB** to test program.

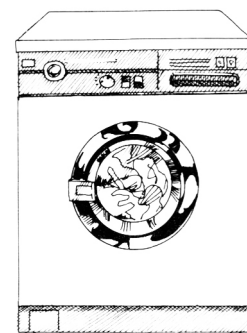
Describe what happens in this program. How could the motor be included in this program?



LEGO Lines	IN	7	6	5	4	3	2	1	0	OUT
<b>REPEAT</b>										10
lighton		0	1	0	0	0	0	0	0	
lightoff		0	0	0	0	0	0	0	0	
<b>ENDREPEAT</b>										

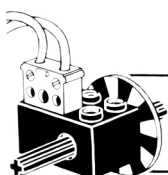
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A washing machine manufacturer requires a control program which will rotate the drum one way for 10 seconds and then rotate it the opposite way for 10 seconds. This sequence needs to be repeated 4 times.



Using a light brick (*representing an on/off light*) and a LEGO motor (*representing the motor turning the drum*), write a program which solves this problem.

Keep a record, on a Program sheet, of how your program develops.



a i s e c t



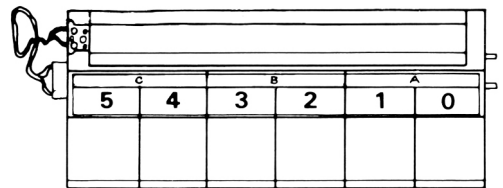
### You will need

- A model
- A manual controller
- Resources booklet R6, R16-21
- Timing device (wristwatch)

### You are going to

Learn how mechanical gears can control how quickly a motor turns a shaft.

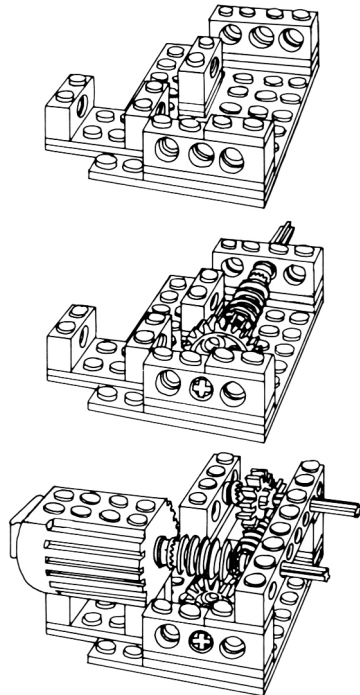
Connect the model to the manual controller.  
 Make sure the connections are properly made.  
 Turn the motor on.  
 The model mechanism (the output shaft) turns more slowly than the motor which is driving it (the input shaft). Why should this happen?



### Build a gearbox like this one (you may need additional materials).

Why do the output shafts of this gearbox have different speeds to the motor?

Discover if axles which turn quickly have a greater or smaller turning force than slower axles. Try slowing them down with your finger. Which is easier to stop?

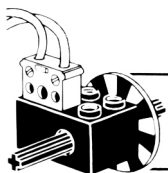
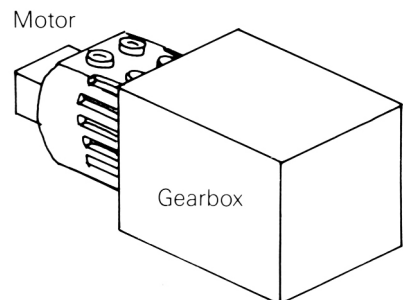


Look at the section in the Resources booklet on gearboxes and drive mechanisms.

### How could you design a gearbox which will make your model move more slowly?

Use sketches and descriptions to record your ideas.

Build and test your design.



a i s e c t

# Assignment: 4a



## Sensing and feedback

# A4a

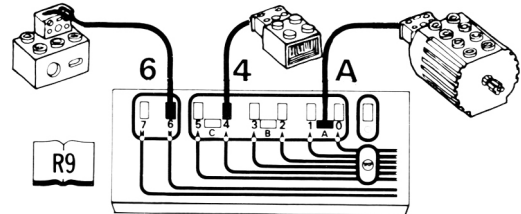
### You will need

- Computer system and LEGO Lines disk
- A model with a light brick, a motor, and an opto-sensor brick
- Resources booklet R7, R9–R12

### You are going to

Learn how to use the opto-sensor brick.

Connect the motor on the model to output bits A.  
 Connect the light brick and opto-sensor to the interface as shown.



On the interface bits 7 and 6 are input bits — that is, bits which let the computer system receive information from its environment.

Is the green indicator light for bit 6 on or off? Place your finger over the sensor slot — the indicator light will change. When you remove your finger it should return to its original state. Connect the opto-sensor to bit 7. Does it behave in the same way?

Describe what you think is happening.

Reconnect the opto-sensor to bit 6 and connect it to your model. Connect the light brick to the model so that it shines into the opto-sensor, but 3 cms away from it.

Load the program called **MLB**. This program is designed to wait for a signal from the opto-sensor before switching the motor on for 2 seconds.

Press **TAB** to run the program and use your finger to trigger the sensor.

R10

	IN							OUT				
LEGO Lines	7	6	5	4	3	2	1	0				
light							0	1	0	0	0	0
REPEAT												
UNTIL		1										
oneway			0	0	0	0	0	1	2			
otherway			0	0	0	0	1	0	2			

R9

## Alter input sense

Pressing **⇓** will take the cursor block down to the third line. Press **f1** to alter bit 6.

Press **TAB** to run the program again.

Can you explain why these two sets of instructions should behave differently?

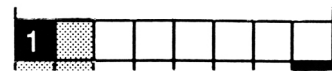
## Alter input line

Disconnect the opto-sensor from 6 and reconnect it to bit 7 on the interface.

Press **⇓** and then press **SHIFT f1** to make bit 6 **any value**.

Press **f0** to alter the value of bit 7 to a 1 and press **TAB**.

R11



*in bit 6 means 'any value'.*

*The sense of bit 6 will not matter when the UNTIL looks for a signal.*

## Counting input signals

Load and run a program called **COUNT**.

This program waits for you to cover (and uncover) the sensor slot 10 times before continuing and turning the motor on.

Alter the program so that you only have to cover and uncover the slot 5 times before the motor is turned on.

R10

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a i s e c t

# Assignment: 4b



## Sensing and feedback

A4b

**You will need**

A model  
 Manual controller  
 Resources booklet R6, R12

**You are going to**

Learn about human sensing and feedback.

### Part A

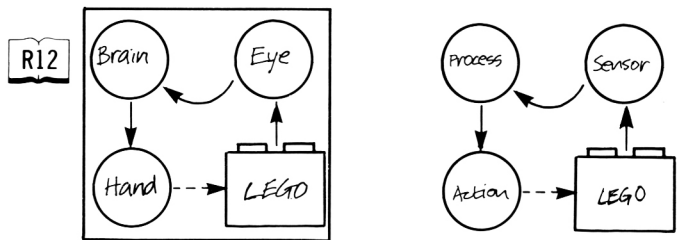
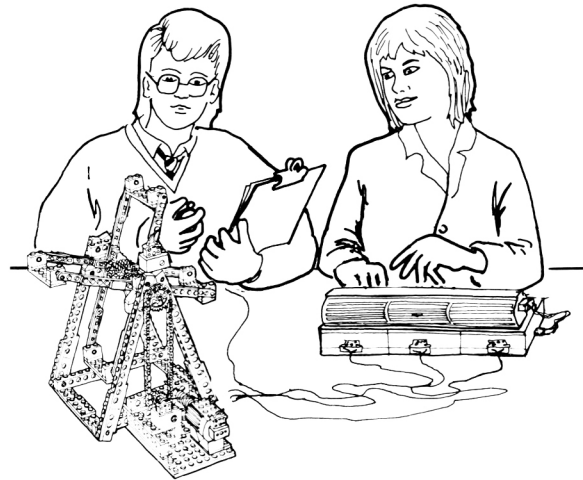
Decide on a task which fits your model (this should take about one minute to complete).

For example, use model 1090 A, the Ferris wheel.

The task is to rotate the wheel so that each seat comes to rest at the bottom in turn so passengers can get on and off.

Use the manual controller and let each member of the group have a try. Make a note of the time it takes for each person to offload all the passengers.

Using the diagram, describe what is happening when a person performs this task (use the keywords *sense*, *process* and *act* in your description).



### Part B

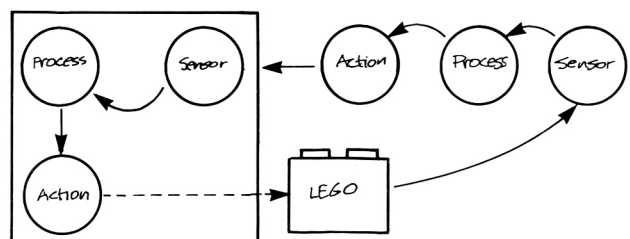
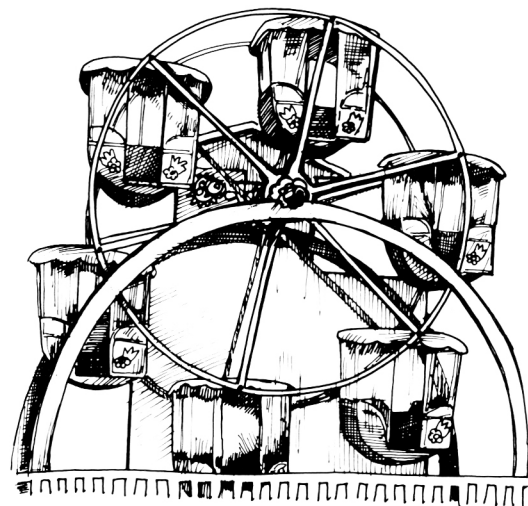
Whatever task you chose, you should now repeat it. This time, however, the person using the manual controller should have their eyes shut, so they cannot see the model.

Another member of the group must now give instructions to the controller so the task can be performed. These might be 'Go forward', 'Back a bit' or 'Whoa!', whatever seems to work.

Again, you should make a note of the time it takes to complete the task.

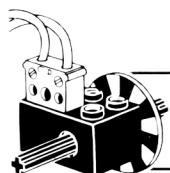
How different were the times it took to complete the task?

Using the diagram, describe what happened (use the keyword *feedback* in your description). Try to explain why the tasks in part B took longer.



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a   i   s   e   c   t



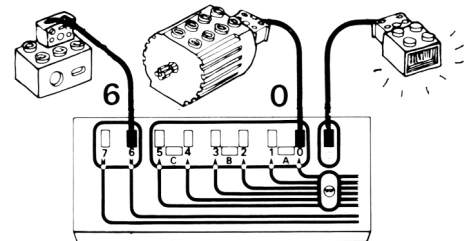
### You will need

- Computer system and LEGO Lines disk
- A motor, a light brick and an opto-sensor brick
- Resources booklet R7-R10

### You are going to

Learn how to design a program which will REPEAT a sequence of instructions UNTIL an input message is sensed.

Connect the motor, the light brick and the opto-sensor brick to the interface as shown.



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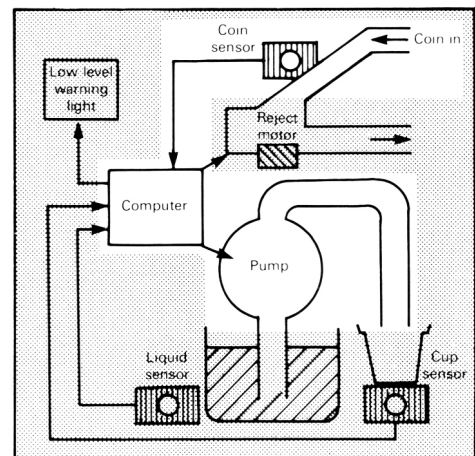
In a drinks dispensing system, a drink is to be pumped out only when a coin has been inserted. Design a program to solve this problem using the LEGO motor as the pump motor and the light brick and opto-sensor as a coin detector.

Check that the opto-sensor is connected to input bit 6.

Connect a light brick to the 4 v output supply and arrange it so that when the light shines into the opto-sensor the indicator light for bit 6 is off.

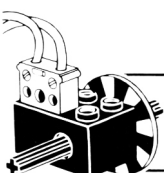
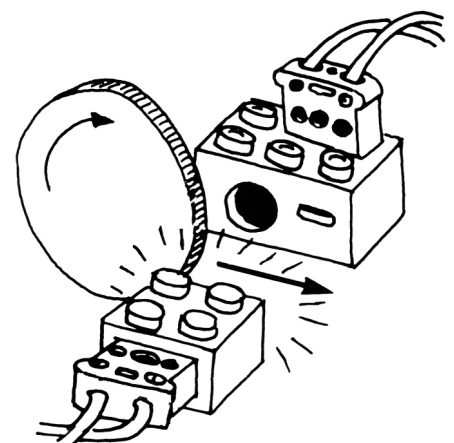
Load program SEVEN.

Press **TAB** to test the program. Cover the sensor to simulate a coin passing.



LEGO Lines	IN							OUT	
	7	6	5	4	3	2	1	0	
<b>REPEAT</b>									
off		0	0	0	0	0	0	0	
<b>UNTIL</b>	1								
motoron		0	0	0	0	0	0	1	2

Use a hard copy of this program and describe what would happen in an actual drinks dispenser system once a coin had been detected.



a i s e c t

# Assignment: 5b



Computer control

A5b

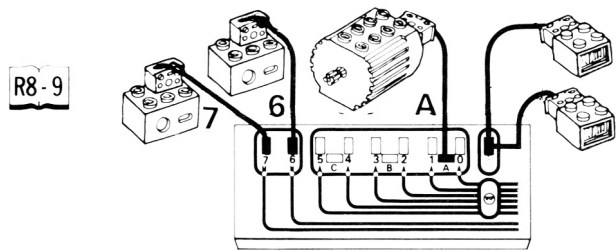
**You will need**

- Computer system and LEGO Lines disk
- A motor and two opto-sensor bricks and two light bricks
- Resources booklet R7-R10

**You are going to**

Learn how to design a program which requires two separate inputs to be sensed before an action is performed.

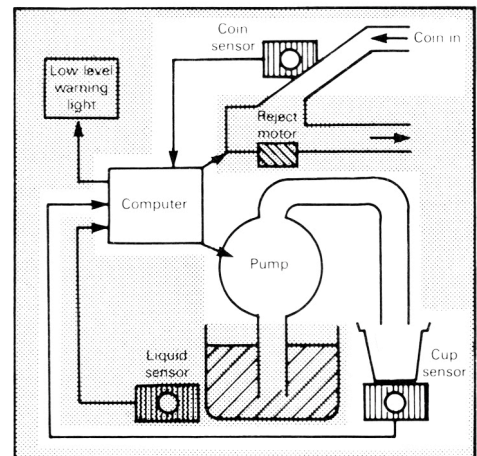
Connect the motor, the opto-sensors and the light bricks to the interface as shown.



**A program is required which will not dispense drinks until a coin is inserted and a cup is in place.**

Connect the sensors to input bits 6 and 7. Make sure both indicator lights for bits 6 and 7 are off by placing your finger over the sensors as necessary, or by using the light brick as in A5a.

Connect the motor to output bits A.

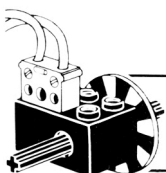
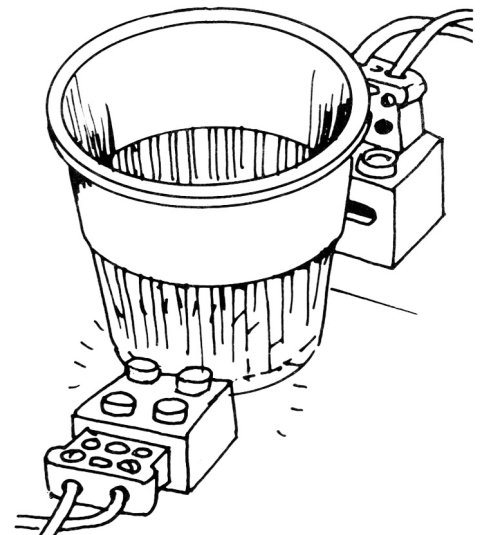
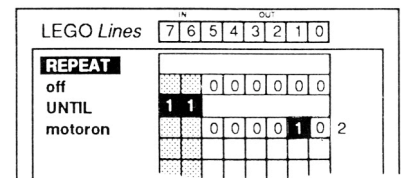


Load program **EIGHT**.

The opto-sensors are used to sense the presence of a coin and a cup.

Press **TAB** to test the program.

Use a hard copy of the program and describe what would happen in an actual drinks dispenser if the program were run.



a i s e c t

# Assignment: 5c



Computer control

A5c

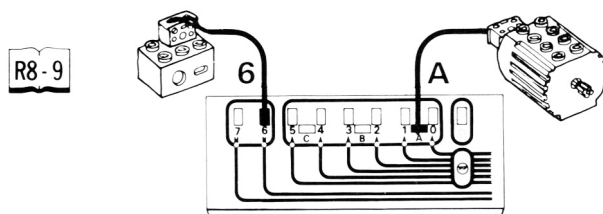
**You will need**

- Computer system and LEGO Lines disk
- A motor and an opto-sensor brick
- Resources booklet R7-R10

**You are going to**

Learn how to design a program which will skip over a sequence of instructions until the right input is sensed.

Connect the motor and opto-sensor to the interface as shown.

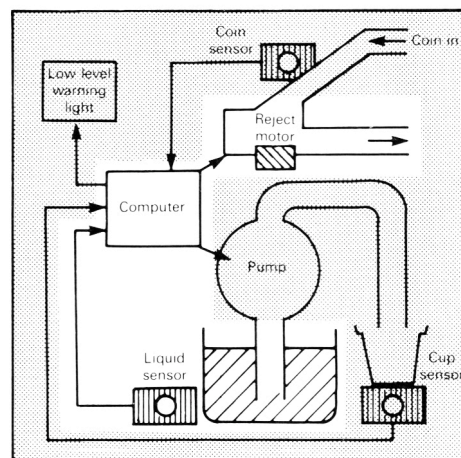


**A program is required which will reject a coin if the liquid has been used up.**

Condition the opto-sensor so that the indicator light on the interface is off at the start.

You could use a light brick (as before) or you could use your finger to activate the 'liquid sensor'.

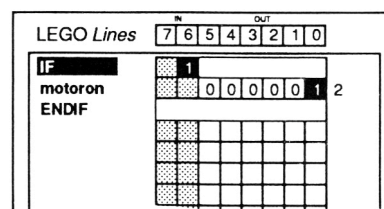
*The LEGO motor represents the motor which rejects the coin.*



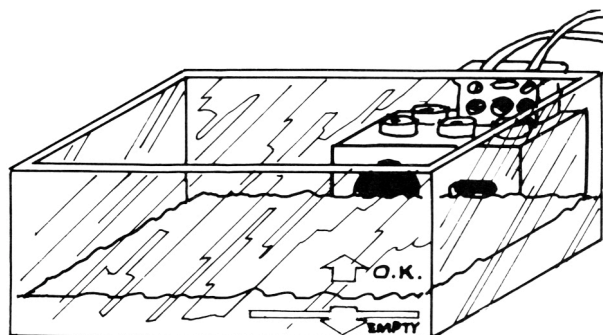
Load program **NINE**.

Press **TAB** to test the program.

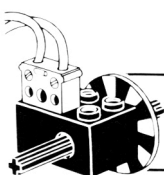
Obtain a hard copy of the program and describe how it controls the motor.



Note that the motor does not come on (to reject the coin) until the sensor detects that the liquid has been used up.



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a i s e c t



# Assignment: 5d



Computer control

A5d

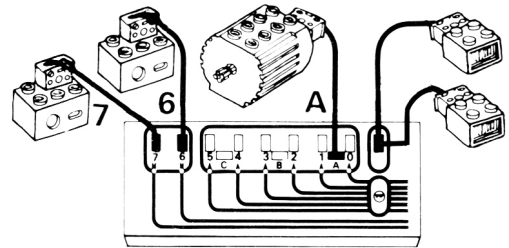
**You will need**

- Computer system and LEGO Lines disk
- A motor, two light bricks and two opto-sensor bricks
- Resources booklet R7-R10

**You are going to**

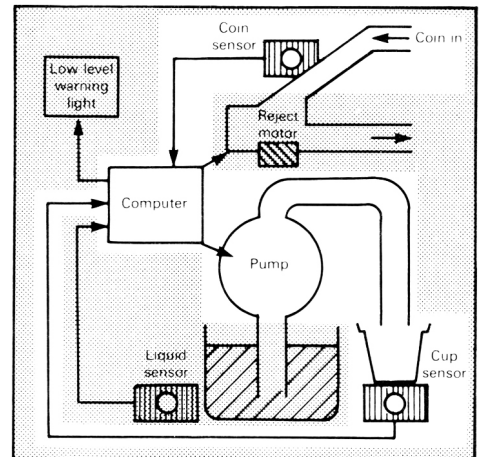
Learn how to design a program which will execute a sequence of instructions if two inputs are sensed.

Connect the light bricks, the motor and the opto-sensor bricks to the interface as shown.



**A program is required which will only turn on the pump if a coin is inserted and a cup is in place.**

Condition sensors so that the indicator lights on the interface are both off.



Load program **TEN**.

Press **TAB** to test program.

Describe what happens.

Can you account for why the program 'appears' not to work?

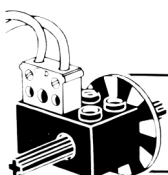
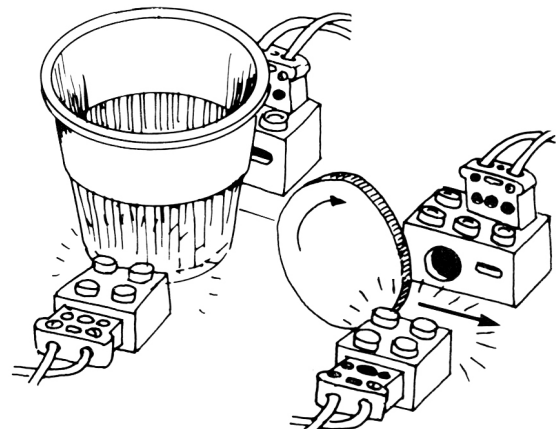
LEGO Lines		IN							OUT		
		7	6	5	4	3	2	1	0	1	2
<b>IF</b>	1	1									
motoron		0	0	0	0	0	0	1	2		
<b>ENDIF</b>											

**Note**

The motor should *not* come on.

Condition the sensors so that the motor does come on.

Describe how you did this.



a i s e c t



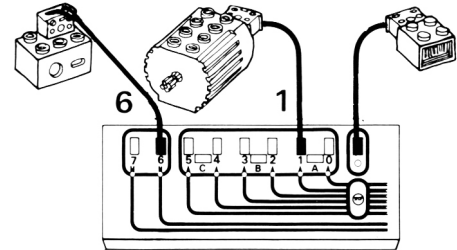
### You will need

- Computer system and LEGO Lines disk
- A motor, a light brick and an opto-sensor brick
- Resources booklet R7-R10

### You are going to

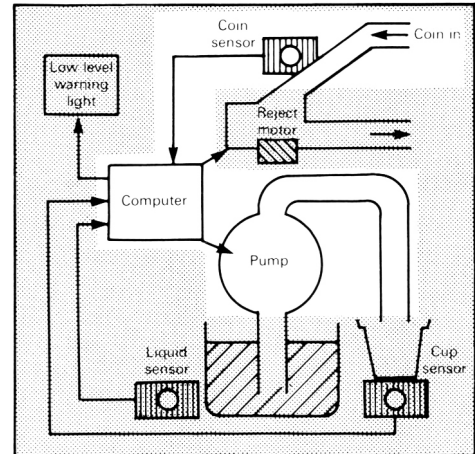
Learn how to design a program which continually looks for an input and, when that input is sensed, executes a sequence of instructions.

Connect the motor, light brick and opto-sensor brick to the interface as shown.



**A program is required which continually looks for a coin and dispenses a drink when the coin is inserted.**

Condition the sensor so that the indicator light on the interface is off.



Load program **ELEVEN**.

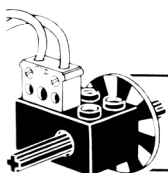
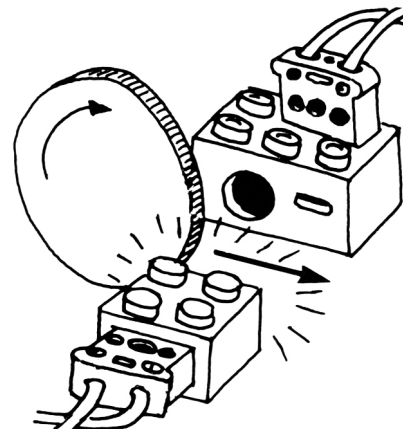
Press **TAB** to test the program.

When you condition the sensor to be on, the program will turn the motor on, then off. You can condition the sensor to be off again to simulate waiting for a coin to be inserted.

This will be repeated until the **ESCAPE** key is pressed.

Copy this program onto a Program sheet and explain how it differs from previous examples in this assignment.

LEGO Lines	IN	OUT						
	7	6	5	4	3	2	1	0
<b>REPEAT</b>								
<b>REPEAT</b>								
<b>UNTIL</b>								
<b>motoron</b>		0	0	0	0	1	0	2
<b>motoroff</b>		0	0	0	0	0	0	0
<b>FOREVER</b>								



a i s e c t

# Assignment: 5f



Computer control

A5f

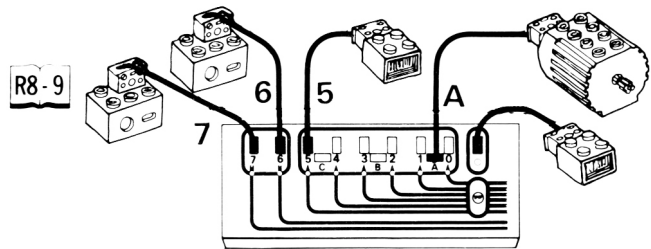
You will need

- Computer system and LEGO Lines disk
- A motor, two light bricks and two opto-sensor bricks
- Resources booklet R7-R10

You are going to

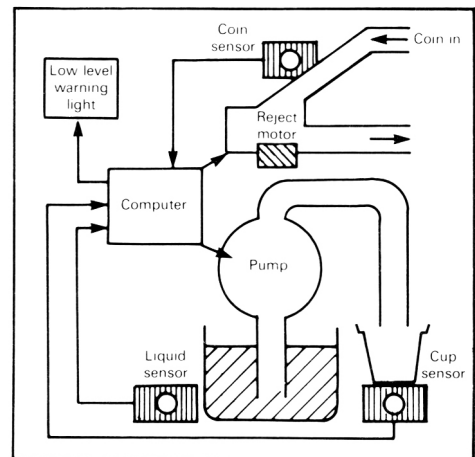
Learn how to design a program which executes a sequence of instructions when an input is sensed. As part of those instructions another input will be tested and, if it is on, the appropriate action will be performed.

Connect the motor, light bricks and opto-sensor bricks to the interface as shown.



A program is required which looks for a coin and dispenses a drink when the coin is inserted. The program should then check the liquid level and, if it is too low, a warning light should be lit.

Condition the opto-sensors to be off.



Load program TWELVE.

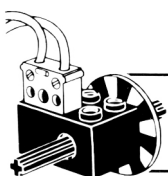
Press **TAB** to run the program.

**ESCAPE** will stop the program.

LEGO Lines	IN							OUT			
	7	6	5	4	3	2	1	0			
REPEAT											
REPEAT											
UNTIL											
motoron		1									2
motoroff											
IF											
lighton		1									
ENDIF											
FOREVER											

Copy this program onto a Program sheet and describe what would happen in an actual drinks dispenser if it were run.

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a i s e c t



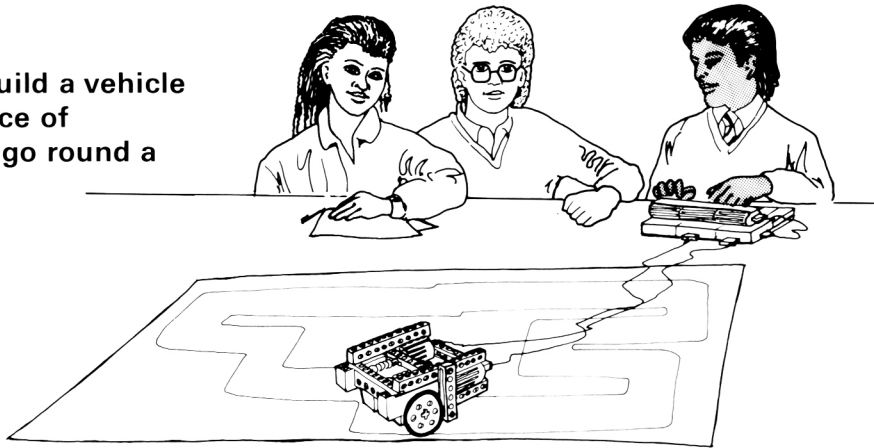
### You will need

- LEGO 1090 Kit
- Manual controller
- Resources booklet R6, R15-21
- A1 sheet of paper

### You are going to

**Design and make a vehicle which you can then control.**

Your group is required to build a vehicle and then to write a sequence of instructions to enable it to go round a course.



### Building the vehicle

- R15** shows some vehicle structures
- R16** shows some drive mechanisms
- R17** shows some steering mechanisms

Using these ideas, and ideas of your own, build the vehicle.

### Draw a route

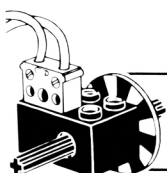
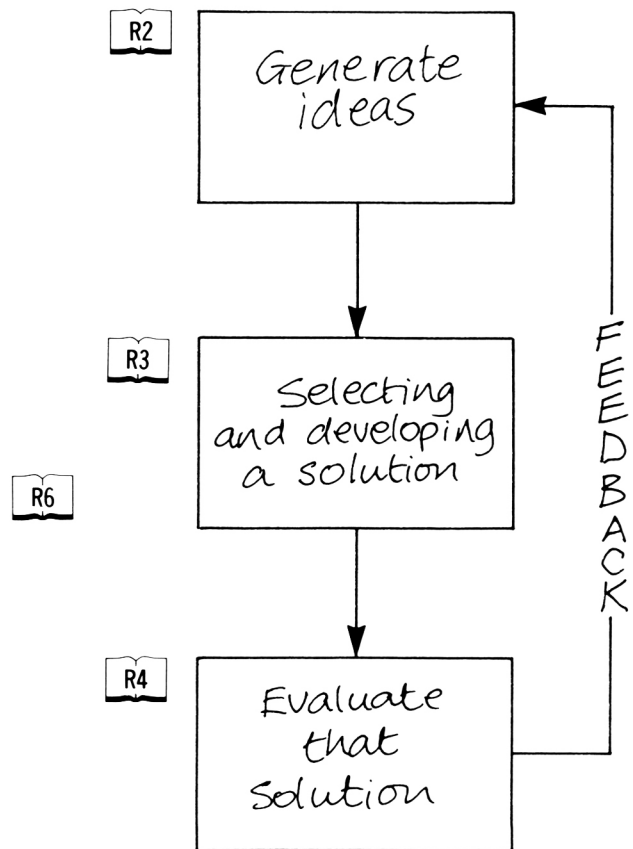
On the large piece of paper, draw a course for your vehicle to go round.

### Test your model

Using the manual controller, test whether your vehicle is capable of going round at least part of the course. If it isn't, you will have to change your design until it can. This is the *feedback* part of the design process.

### Write a program

Using a Program sheet, write a sequence of instructions which would let somebody else (from another group) make your vehicle follow the course you have drawn.



a i s e c t

# Assignment: 7



## Solving a problem

**A7**

You will need

Resources booklet  
Your results from Assignment 6.

This is a model which will help you solve a problem.

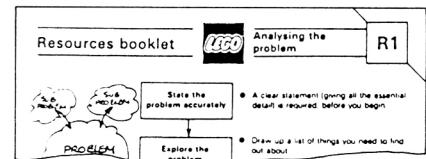
### Actions

### Outcomes

### Further explanations in

Analyse the problem

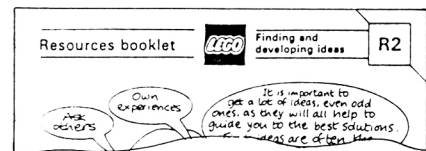
Criteria list



Analysing the problem

Finding ideas

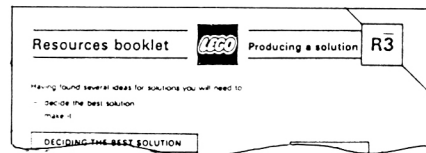
Several ideas



Finding and developing ideas

Select and develop the best solution

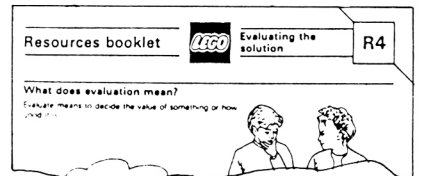
working solution



Producing a solution

Evaluate your solution

test results



Evaluating the solution

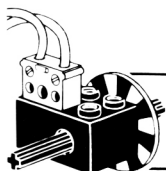
Communicate your work

a report



Communicating a solution

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a i s e c t

# Assignment: 8



Designing a structured program

A8

You will need

A washing machine model 1090 C  
Computer system and LEGO Lines disk  
Resources booklet R1-R5, R10-R14

You are going to

Use the problem-solving process to produce a structured program in order to control a washing machine.

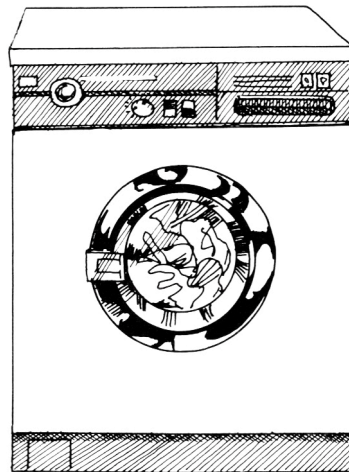
## Problem solving

A program is required which turns the motor and the indicator light of a washing machine on when the door is closed and the switch is on.

The washing machine should turn off when the door is opened.

## Resources available

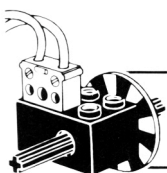
The Assignments you have already completed  
Resources booklet



## Further problems

Turn the washing machine on if the door is closed and the switch is on. First execute a wash cycle (and light) and then spin (and light).

Add an emergency switch facility which shuts the machine off.



a   i   s   e   c   t

# Assignment: 9a



Designing a programmed system

A9a

You will need

- 1090 LEGO Set
- Computer system and LEGO Lines disk
- Resources booklet
- Assignments you have completed

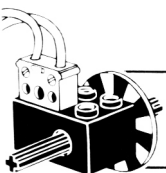
You are going to

Use the problem-solving process.

## Sliding Door

A supermarket requires a sliding door system which will allow customers to pass in and out with ease but which remains shut at other times to save heat and energy.

As a development team for *HyperDoor (Electronic Doors) plc* your job is to prepare a report and demonstrate a solution to this problem.



a i s e c t

# Assignment: 9b



Designing a programmed system

A9b

You will need

- 1090 LEGO Set
- Computer system and LEGO Lines disk
- Resources booklet
- Ideas booklet
- Assignments you have completed

You are going to

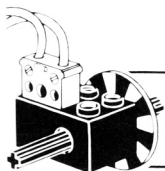
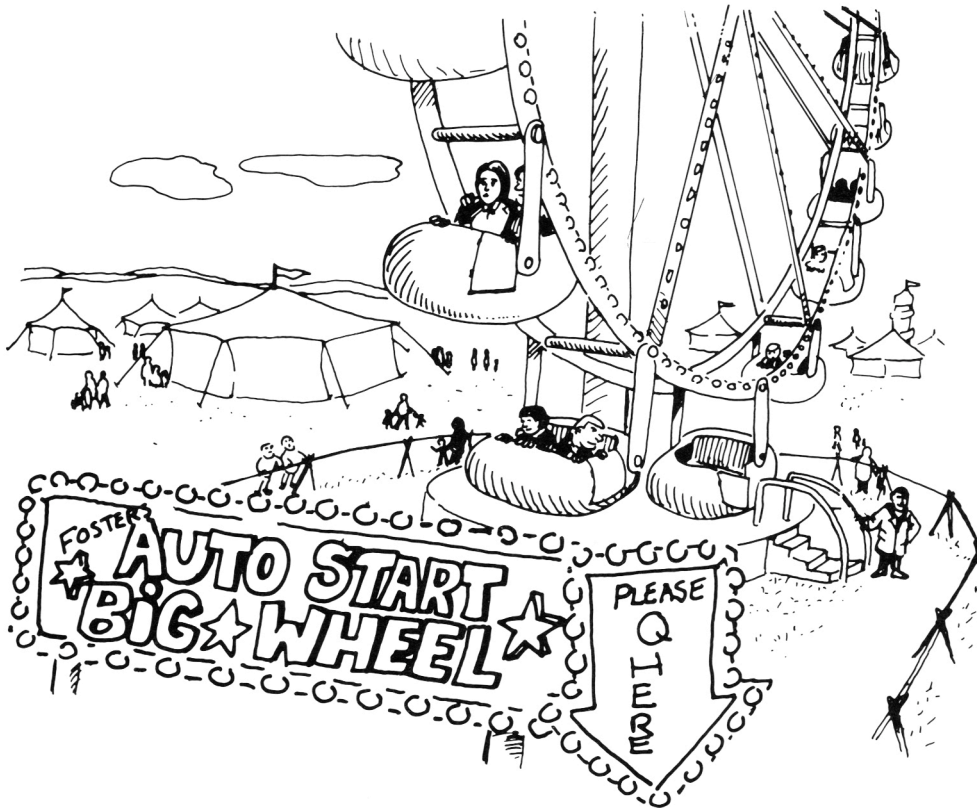
Use the problem-solving process.

## Automatic Ferris wheel

A fairground equipment manufacturer has provided your design team with a contract to develop an automatic system for controlling a Ferris wheel ride.

The ride should be safer, more economic and more appealing than the present manual system.

You are required to provide a report and demonstration of a model of your best solution.



a i s e c t



# Assignment: 9c



Designing a  
programmed system

A9c

You will need

- 1090 LEGO Set
- Computer system and LEGO Lines disk
- Resources booklet
- Assignments you have completed

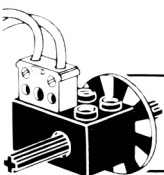
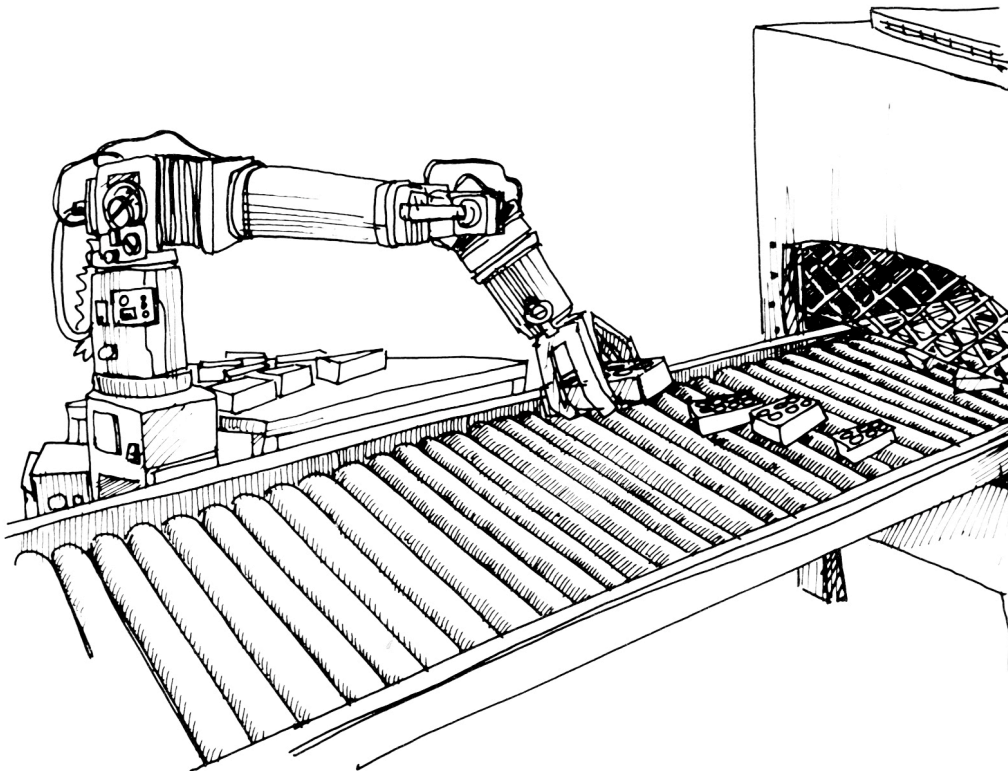
You are going to

Use the problem-solving process.

## Robot Arm

A manufacturer requires a device which will pick LEGO bricks up from a conveyor belt and place them on a platform situated 10 cms from the conveyor.

Your team must provide a report and a model of this device.



a i s e c t

# Assignment: 9d



Designing a  
programmed system

A9d

You will need

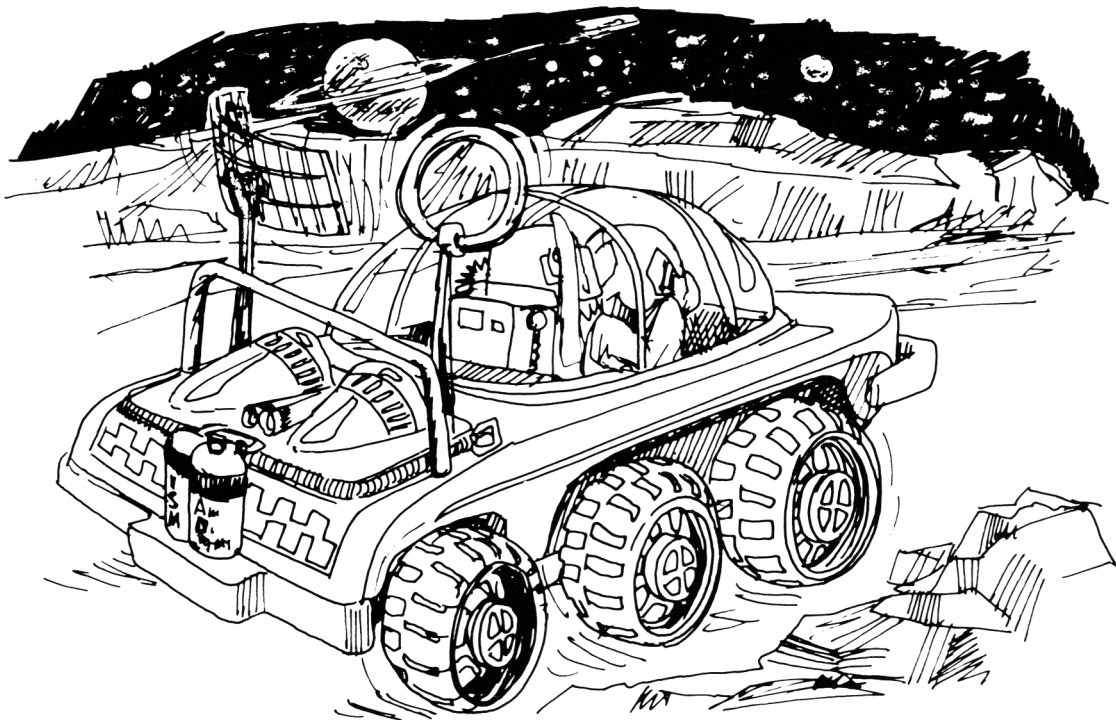
1090 LEGO Set  
Computer system and LEGO Lines  
disk  
Resources booklet  
Assignments you have completed

You are going to

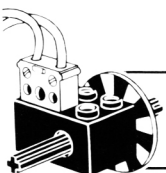
Use the problem-solving  
process.

## Space vehicle

Your development team must prepare a report and build a model of a mobile space vehicle. It should be capable of avoiding obstacles in its path.



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You will need

- 1090 LEGO Set
- Computer system and LEGO Lines disk
- Resources booklet
- Assignments you have completed

You are going to

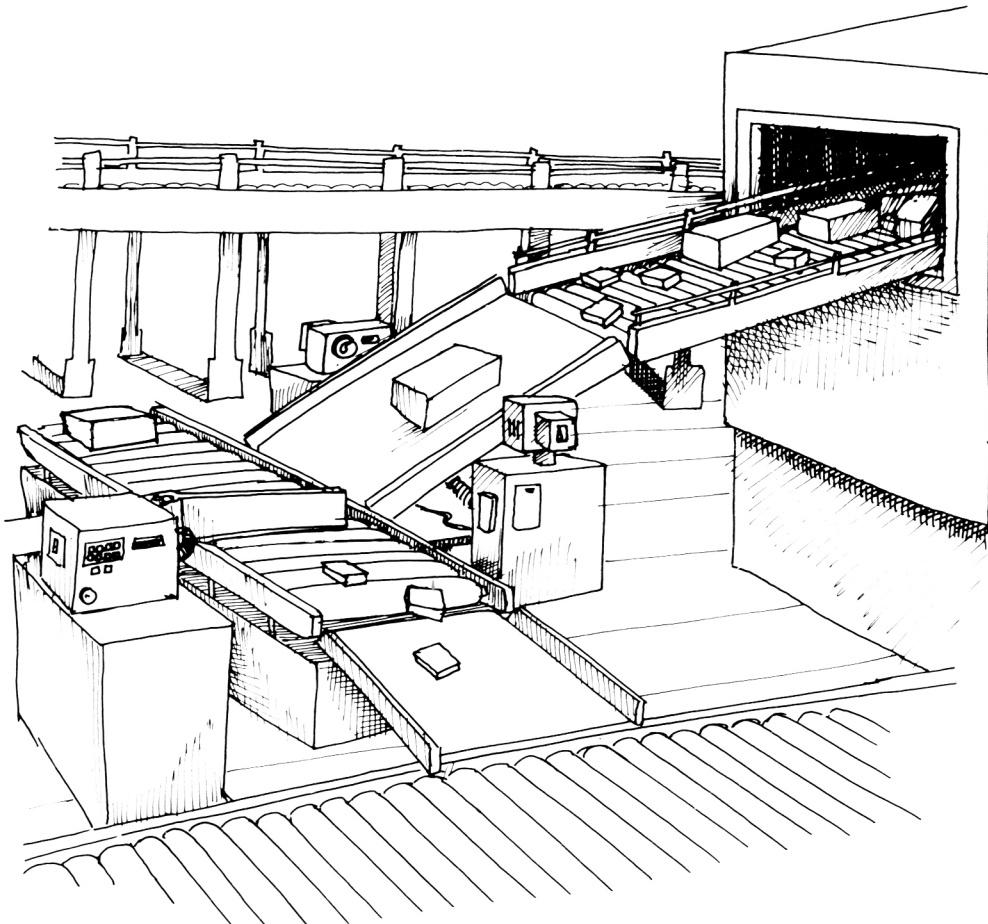
Use the problem-solving process.

## Conveyor system

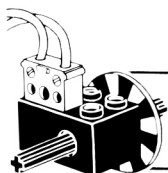
A manufacturer wishes to install a computerised conveyor system in the factory.

The system must be capable of sorting out large boxes on the conveyor from smaller ones.

Your team should build a model of the most appropriate solution, and submit a report on your work to the management.



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# Assignment: 9f



Designing a programmed system

A9f

You will need

- 1090 LEGO Set
- Computer system and LEGO *Lines* disk
- Resources booklet
- Assignments you have completed

You are going to

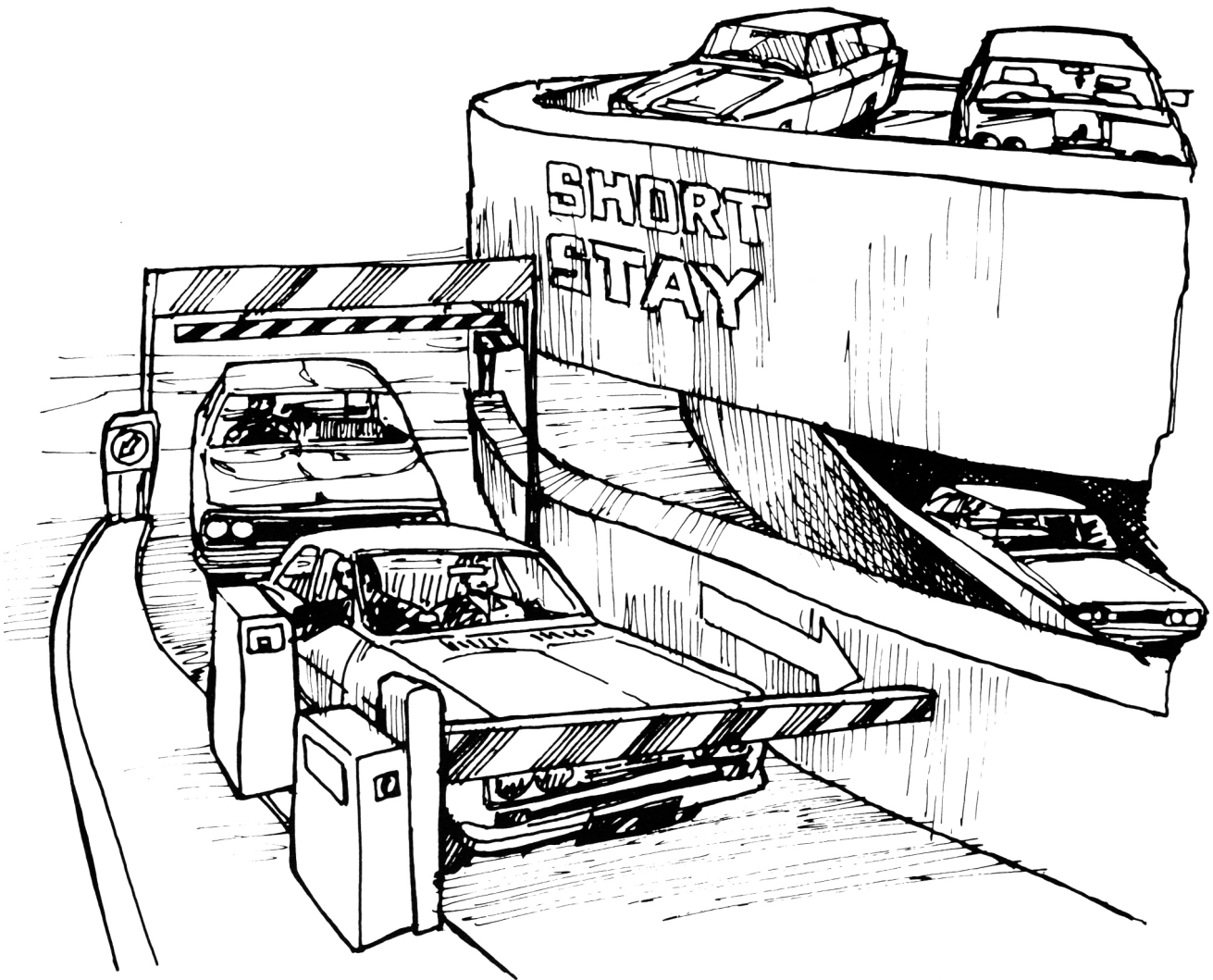
Use the problem-solving process.

## Car Park Barrier

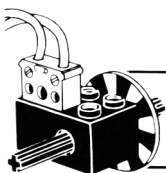
Design an automatic barrier for a multistorey car park.

Care must be taken to ensure that the system your team suggests is efficient and safe.

A model and a report are required.



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a i s e c t



You will need

- 1090 LEGO Set
- Computer system and LEGO Lines disk
- Resources booklet
- Assignments you have completed

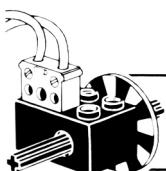
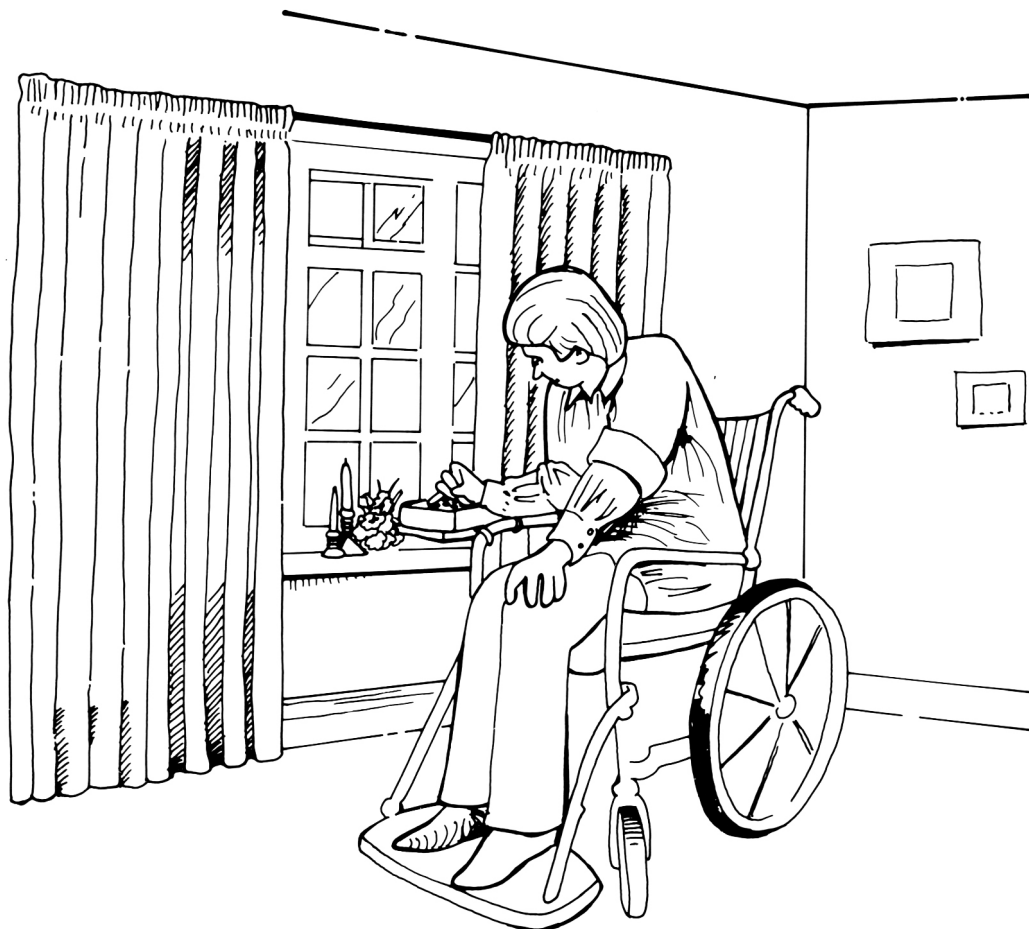
You are going to

Use the problem-solving process.

### Automatic Curtains

Your team has been commissioned to design a set of curtains which open and close automatically. These would be particularly useful to elderly or disabled people.

Prepare a report of your work and a model of your solution.



a		i		s		e		c		t	
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# Assignment: 9h



Designing a  
programmed system

A9h

You will need

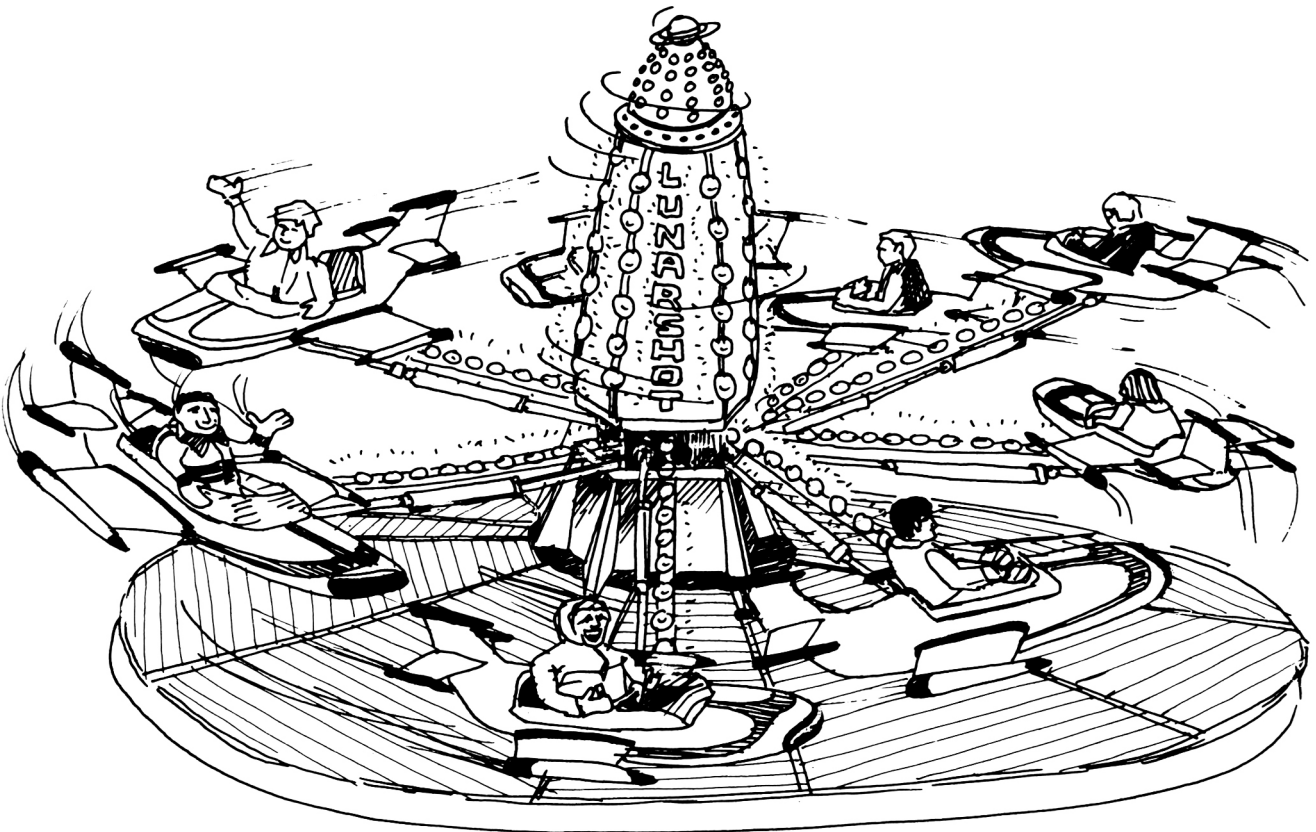
1090 LEGO Set  
Computer system and LEGO Lines  
disk  
Resources booklet  
Assignments you have completed

You are going to

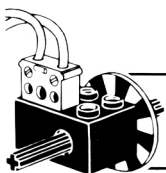
Use the problem-solving  
process.

## Roundabout

A leisure park wishes to install an automatically controlled roundabout. They have commissioned your team to produce a working model and a report of your design.



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a i s e c t

# Assignment: 9i



Designing a programmed system

A9i

You will need

- 1090 LEGO Set
- Computer system and LEGO *Lines* disk
- Resources booklet
- Assignments you have completed
- Plasticine block

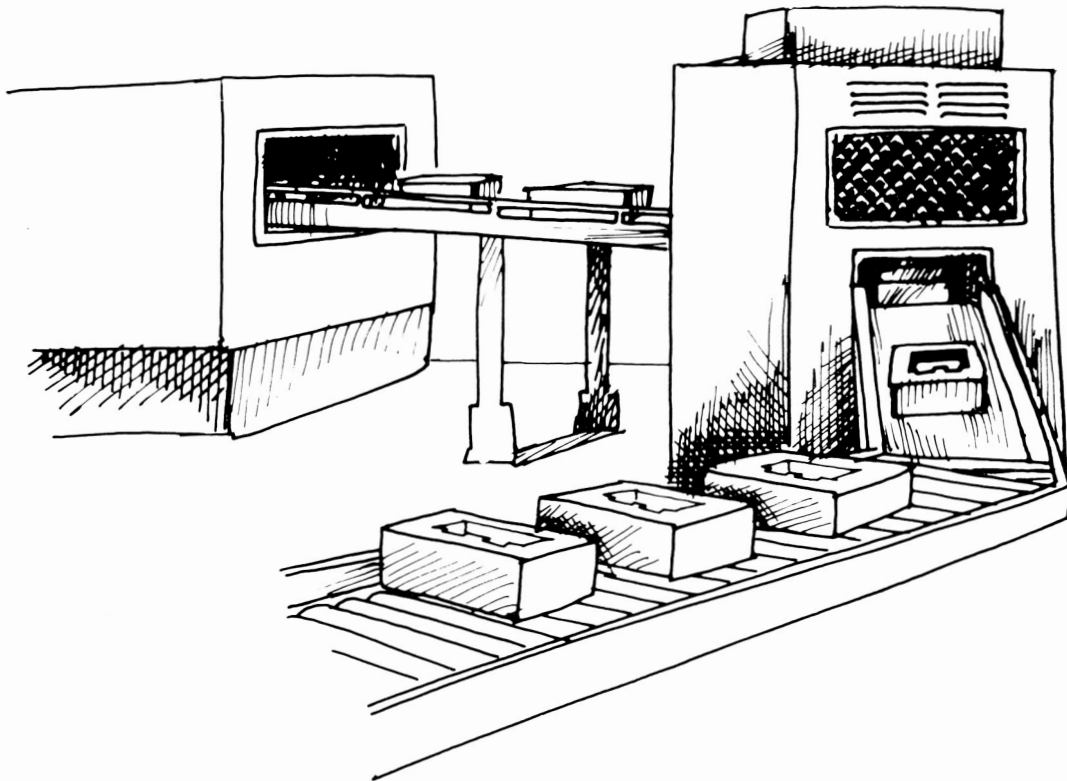
You are going to

Use the problem-solving process.

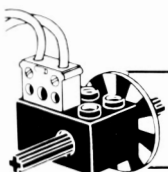
## Pressing machine

Your team should design a device which will automatically stamp the pattern of a LEGO brick onto a block of plasticine when it is placed onto a platform.

A report and a working model are required.



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a i s e c t



You will need

- 1090 LEGO Set
- Computer system and LEGO Lines disk
- Resources booklet
- Assignments you have completed

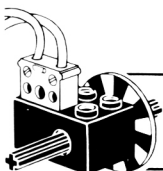
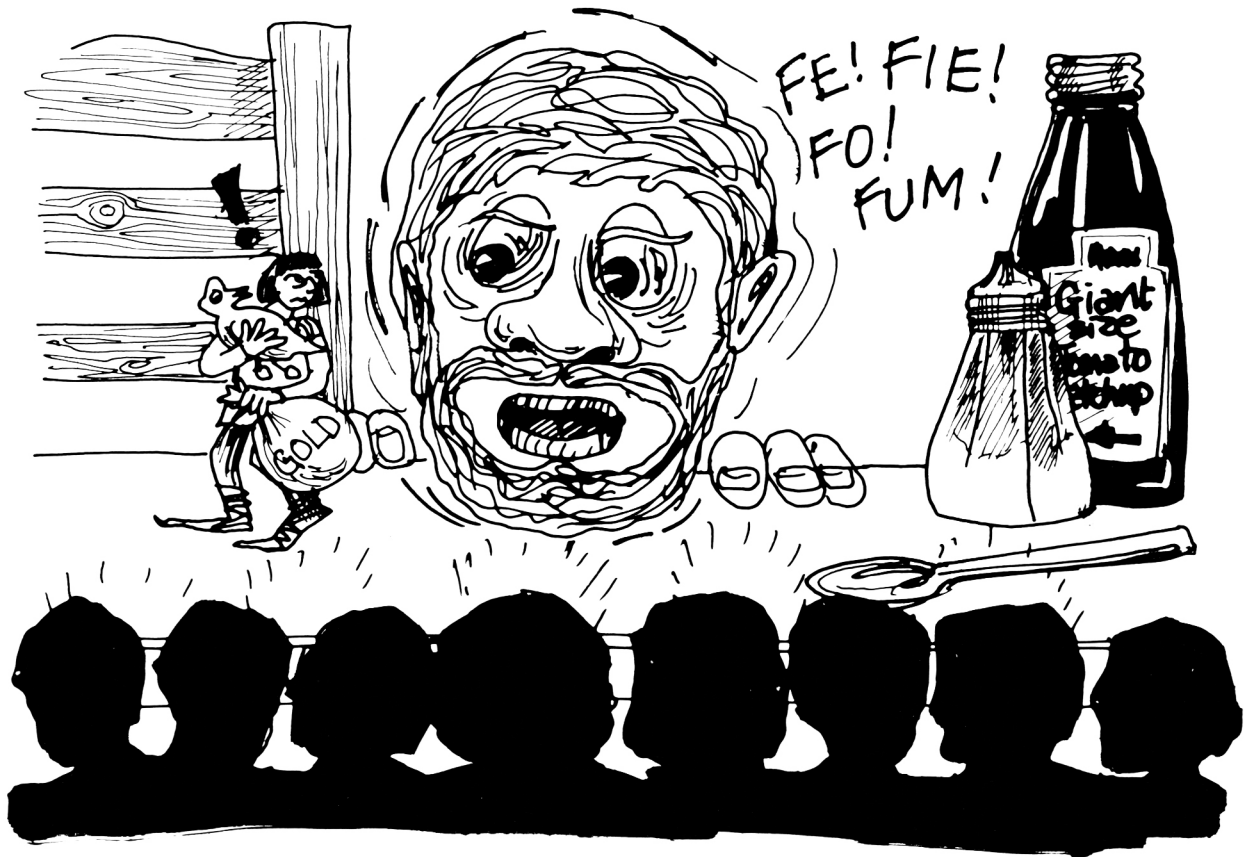
You are going to

Use the problem-solving process.

Stage Effect

Your team has been commissioned to design a head to be mounted on a wall as part of a fantasy play. The head is required to 'come alive' each time one of the cast passes a certain spot.

Prepare a report of your ideas and a working model.



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**LEGO UK Limited**

*EDUCATIONAL DIVISION*

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